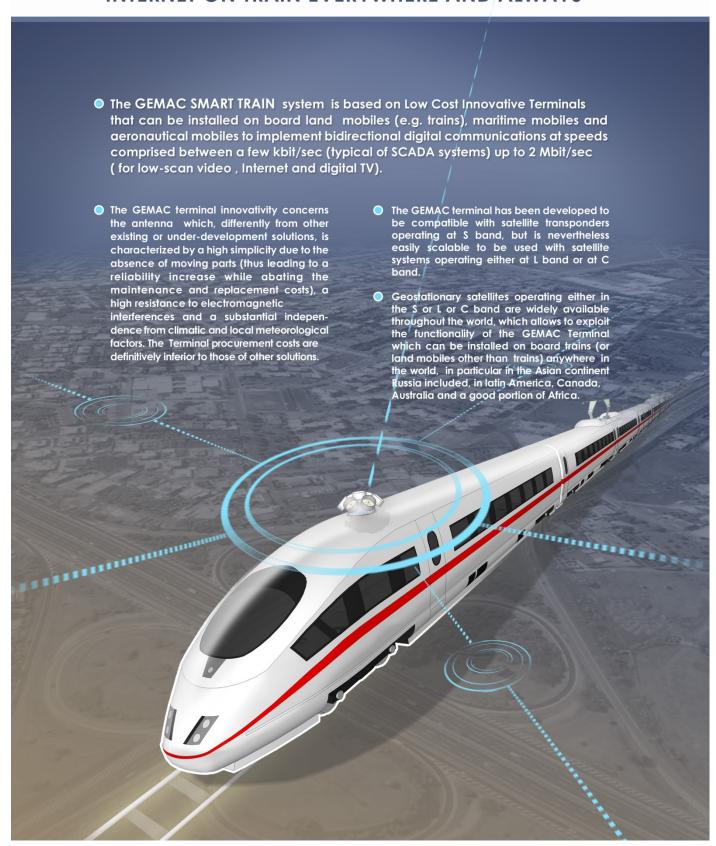


GEMAC SMART TRAIN INTERNET ON TRAIN EVERYWHERE AND ALWAYS





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TECHNICAL DESCRIPTION

The high efficiency of the system has been achieved divind the visible sky hemisphere in N angular sectors assigning to each of them an elementary radiator and rigidly connecting these radiators on a supporting structure in such a way to obtain the wanted connectivity with a geostationary satellite.

The radiating elements are interconnected with the Terminal transceiver by means of a MEMS switch matrix, being the high technology MEMS switches characterized by low RF losses, switching delays of the order of 10 microseconds, and a power handling capability in the 1 to 10 W range.

An open-loop prediction algorithm defines the

angular coordinates of the satellite-to-mobile line of sight in the mobile reference system. The prediction is compared to the time-varying directions (in presence of the mobile motion and attitude variations) of the individual radiating elements boresights.

The control system selects, and activates, the radiating element which exhibits the least angular distance from the satellite-to-mobile line of sight.

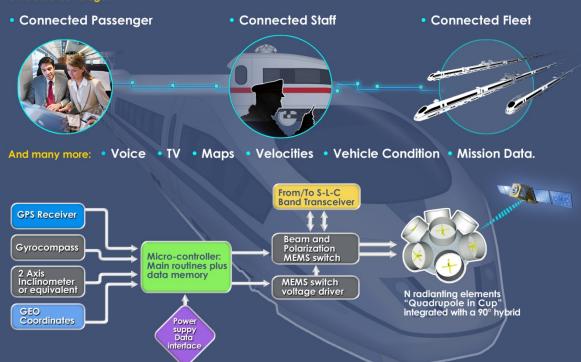
The Control System processes the following data:

- The geographical position of the mobile; given by a GPS receiver
- The instantaneous direction of the mobile given by a compass
- The instantaneous mobile attitude in pitch and roll, given by fast inclinometers
 The geostationary satellite orbital coordi nates, generally known in advance and time-stable

The sensors providing the above data can be integrated in the antenna or else can be provided by a mobile navigation system. In a technology demonstrator the control system can be replaced by a notebook, while for production units it will take the form of a microcontroller integrated in a PC board becoming part of the system.

APPLICATIONS

On board coverage:



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